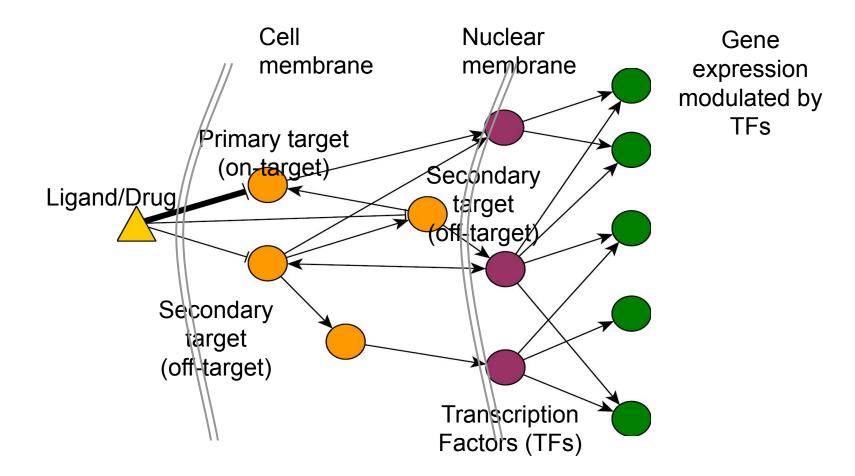
AMIDD Lecture 8: Methods to study biological networks



Dr. Jitao David Zhang, Computational Biologist

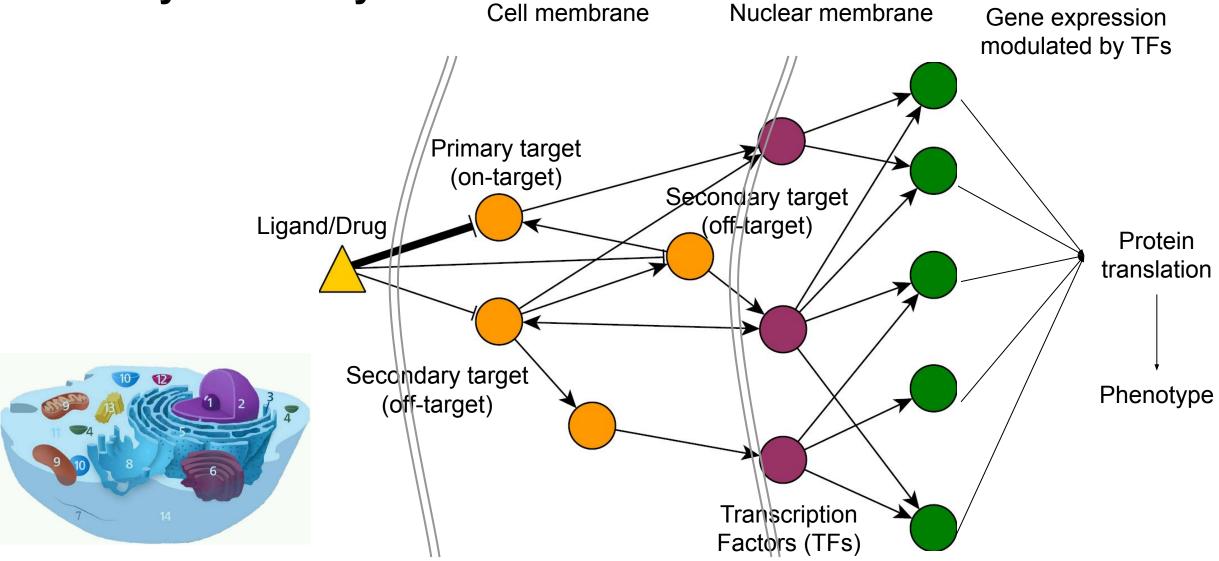
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Outline



- Compartment models and Hill function to model drug-target interactions
- Buttom-up study of biological networks with deterministic and stochastic models
- Introduction to top-down study of biological networks with omics and cellular models

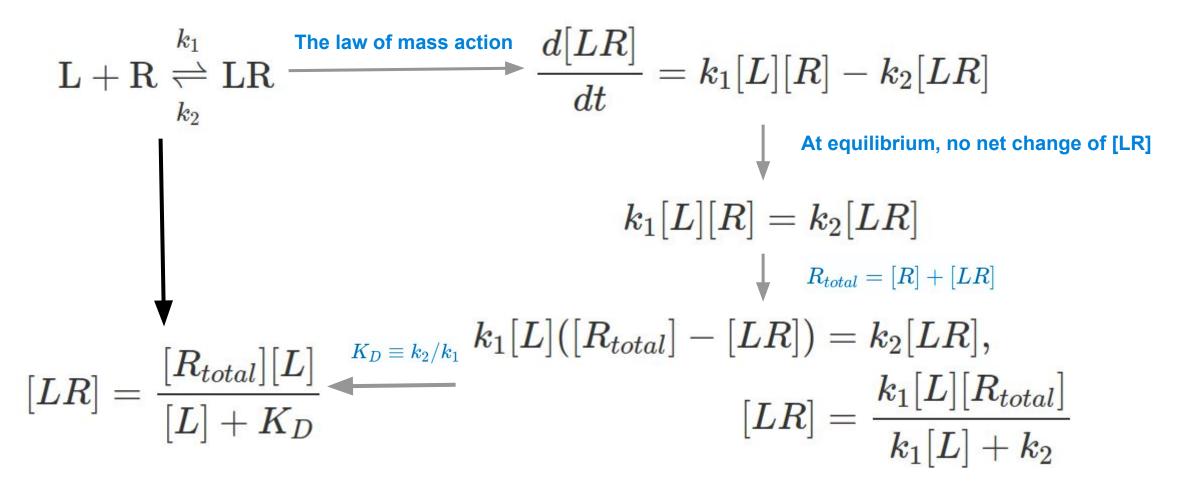
Biological networks interact with drugs and manifest its efficacy and safety



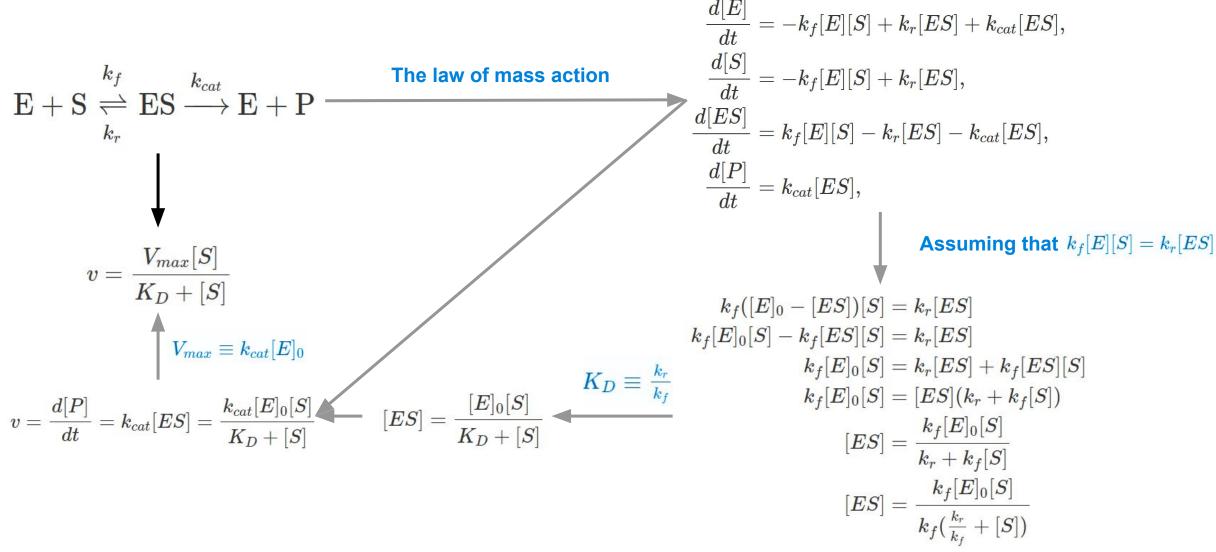
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Ordinary differential equations (ODEs) model ligand-receptor interactions, a common type of edges in biological network



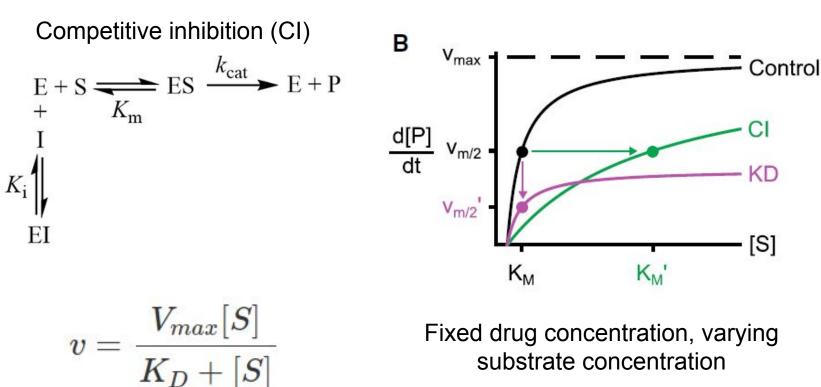
The Michaelis-Menten model of enzyme kinetics, an type of interaction important for drug discovery



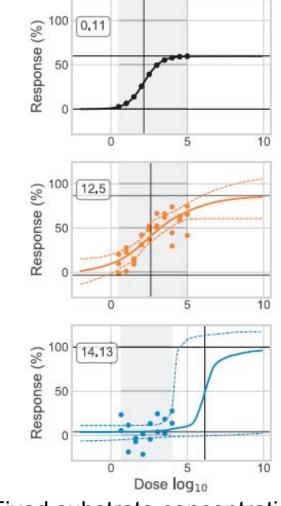
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Many drugs act as competitive inhibitor to reduce the rate of biochemical reactions



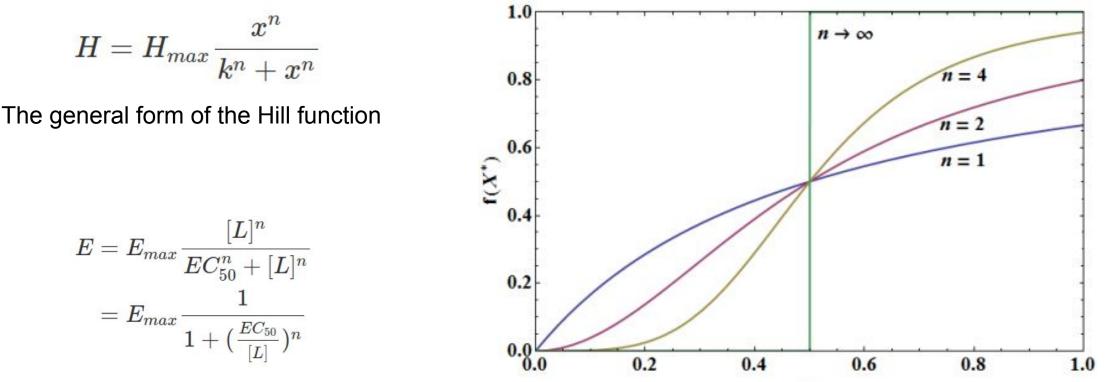
substrate concentration



Fixed substrate concentration, varying drug concentration



The *Hill Function* is a commonly used mathematical model in pharmacology



 X^*

Modelling the dose-dependent effect



Simulation of biological networks with ordinary differential expression: the simplest case

Given the reaction

$$\mathrm{S} + \mathrm{E} \stackrel{k_1}{\underset{k_2}{\rightleftharpoons}} \mathrm{C} \stackrel{k_3}{\longrightarrow} \mathrm{P} + \mathrm{E}$$

Given the initial values and rate constants

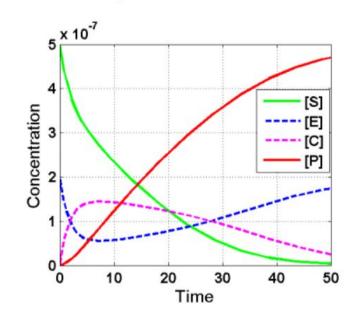
•
$$S(0) = 5e^{-7}$$

• $E(0) = 2e^{-7}$
• $C(0) = P(0) = 0$
• $k_1 = 1e^6$
• $k_2 = 1e^{-4}$
• $k_3 = 0.1$

According to the law of mass action

$$egin{aligned} &rac{d[S]}{dt} = -k_1[E][S] + k_2[C], \ &rac{d[E]}{dt} = -k_1[E][S] + (k_2 + k_3)[C], \ &rac{d[C]}{dt} = k_1[E][S] - (k_2 + k_3)[C], \ &rac{d[P]}{dt} = k_3[C], \end{aligned}$$

It is possible to simulate the concentration changes by time *deterministically*.



See <u>Systems Engineering Wiki (tue.nl)</u> for MATLAB/COPASI codes and *Stochastic Modelling for Systems Biology* by Darren J. Wilkinson



Chemical Master Equations (CME): a particle model of chemical reaction

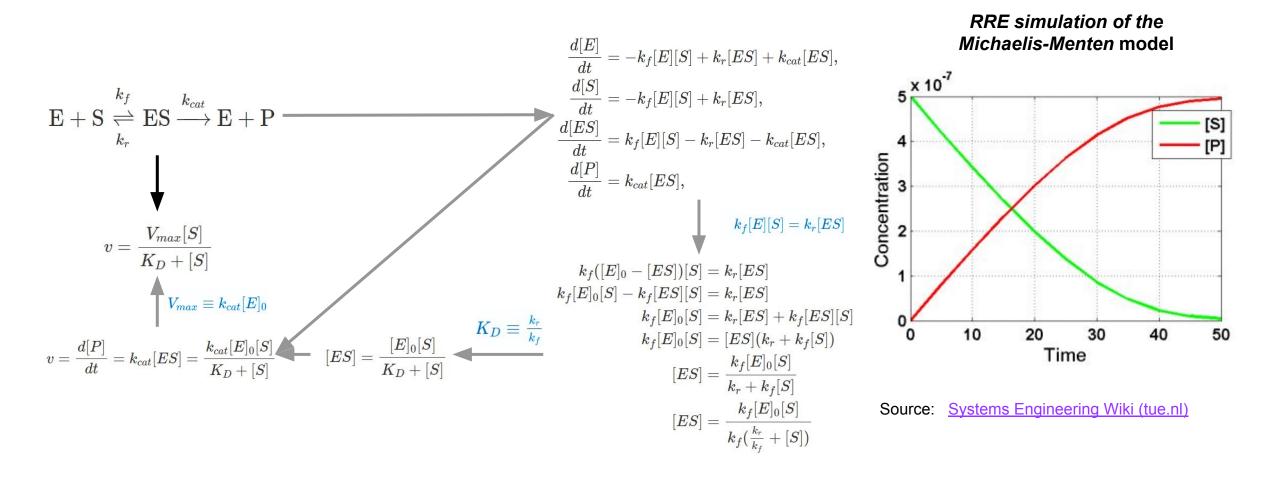
Given the reaction
$$A + B \rightleftharpoons_{k_2}^{k_1} C + D$$
 and the initial condition $X(0) = \begin{bmatrix} K \\ K \\ 0 \\ 0 \end{bmatrix}$ (*K* molecules of species A and of species B respectively)
The state vector $X(t)$ can take at any time point *one* of the values $\begin{bmatrix} K \\ K \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} K-1 \\ K-1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} K-2 \\ K-2 \\ 2 \\ 2 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ K \\ K \end{bmatrix},$

Theoretically we can build an ODE system with *K*+1 equations to model *every state of the reaction*, down to every particle. In reality, the dimension is so high so that a simulation is not feasible.

CME is a set of ODEs, with each ODE representing one possible state of the system. Solution of the *k*th equation at time *t* is a real number giving the probability of system being in that particular state at that time.



Reaction Rate Equations (RRE): the compartment model that we have seen before

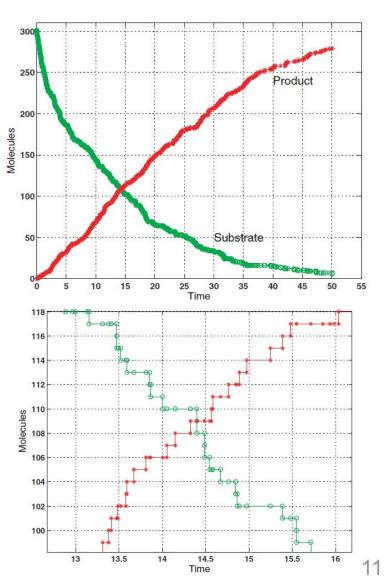


RRE is a set of ODEs, with each ODE representing one chemical species. Solution of the *j*th equation at time *t* is a real number representing the concentration of species *j* at time *t*.

The Gillespie's algorithm and the chemical Langevin equation allow stochastic simulation of biological networks

- The *stochastic simulation algorithm* (exact SSA), also called *Gillespie's algorithm*, allows stochastic simulation of a reaction. It is done in four steps:
 - 1. **initialize** the system with initial conditions
 - 2. Given a state at time *t*, we can define a probability *p* that reaction *j* takes place in the time interval $[t+\tau, t+\tau+d\tau)$. It is the product of two density functions of two random variables: the probability of reaction *j* happens (proportional to the number of substrate molecules), multiplied by the time until next reaction, which is exponentially distributed. This is known as the *Monte Carlo* step.
 - 3. Let the randomly selected reaction happen and update the time.
 - 4. Iterate until substrates are exhausted or simulation time is over.
- Further computation tricks, .e. 'tau-leaping', are used to lump together reactions. The chemical Langevin equation (CLE) further accelerates stochastic simulation by approximating *Poisson* with normal distribution.

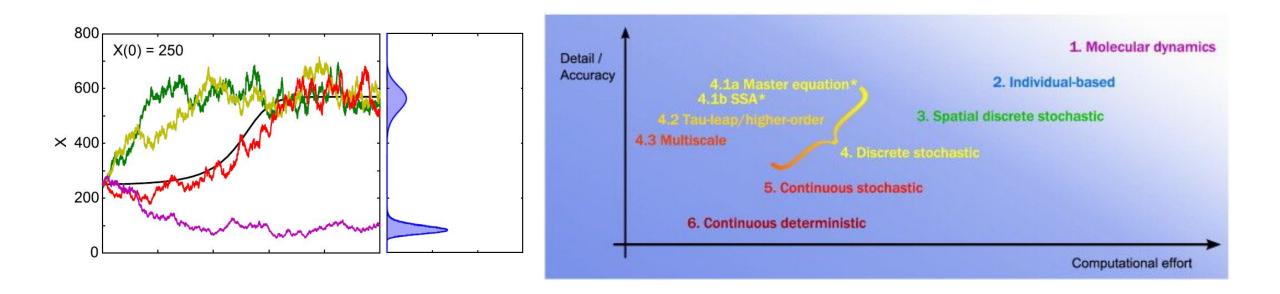
Figure source and further reading: Higham, Desmond J. 2008. "Modeling and Simulating Chemical Reactions." *SIAM Review* 50 (2): 347–68. <u>https://doi.org/10.1137/060666457</u>.





Why stochastic modelling?



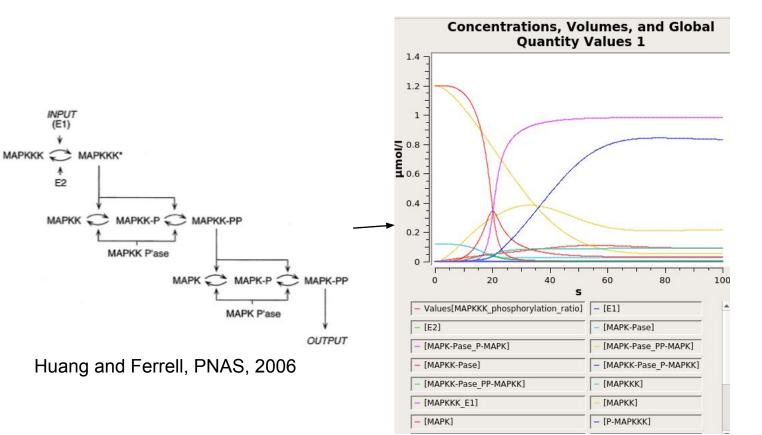


- Stochastic modelling can reveal individual trajectories that are otherwise 'averaged' by ODE models.
- Small systems and single-molecule studies show stochastic behaviour.
- It is possible to consider both extrinsic and intrinsic factors and take them into the model.

Székely and Burrage. 2014. "Stochastic Simulation in Systems Biology." Computational and Structural Biotechnology Journal 12 (20–21): 14–25. Also see Stochastic Modelling for Systems Biology by Darren J. Wilkinson.

Biochemical system simulator COPASI

- COPASI, freely available at <u>http://COPASI.org/</u>, supports two types of simulations: (1) ordinary differential equation (ODE) based simulation, (2) stochastic kinetic simulation, among others using the <u>stochastic Runge-Kutta</u> <u>method (RI5) and Gillespie's algorithm</u>.
- Resources to learn more about stochastic modelling: <u>MIT OpenCourseWare</u> by Jeff Gore, and <u>Stochastic Processes: An</u> <u>Introduction, Third Edition</u> by Jones and Smith. Tutorials also available on <u>the website of</u> <u>European Bioinformatics Institute (EBI)</u>
- Both mathematical concept and software tools are important for detailed analysis of enzymatic reactions, especially in the presence of drugs and/or disease-relevant mutation



ODE-based simulation of dynamics





Five classes of mathematical models drug discovery

Compartment models

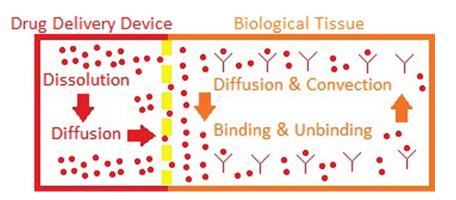
$$rac{d[LR]}{dt}=k_1[L][R]-k_2[LR]$$

Kinetics of ligand-target interaction $\frac{dx}{dt} = \alpha x - \beta xy,$ $\frac{dy}{dt} = -\gamma y + \delta xy,$ The Lotka-Volterra equations modelling predator-prey relationships.

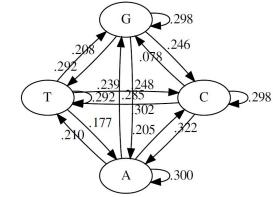
$$\begin{split} \frac{dS}{dt} &= -\frac{\beta IS}{N}, \\ \frac{dI}{dt} &= \frac{\beta IS}{N} - \gamma I, \\ \frac{dR}{dt} &= \gamma I \end{split}$$

The SIR (S=susceptible, I=infectious, R=removed) model of epidemiology

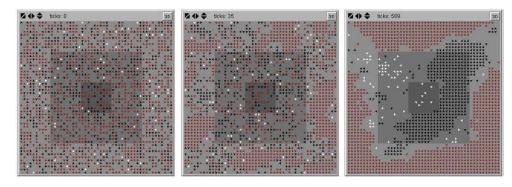
Transport models



Finite state models

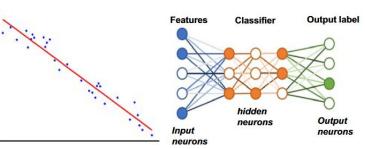


Particle models



A Study on Socio-spatial Segregation Models Based on Multi-agent Systems by Quadros *et al.* (2012). 10.1109/BWSS.2012.14.

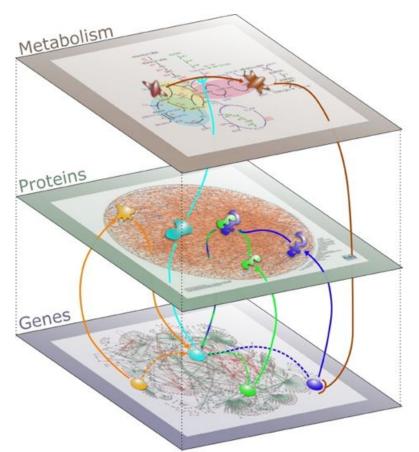
Statistical/machine learning/causal models



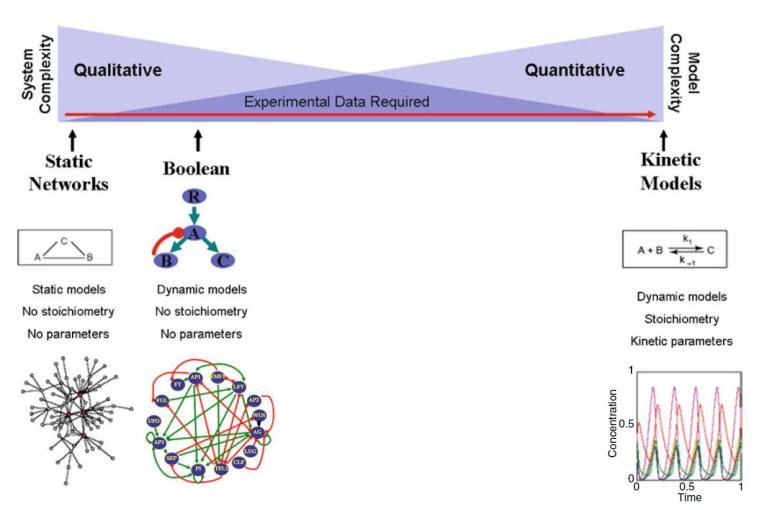
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Modelling biological networks





Stéphane CHÉDIN & Jean LABARRE, www-dsv.cea.fr



Garg, Abhishek, Kartik Mohanram, Giovanni De Micheli, and Ioannis Xenarios. 2012. "<u>Implicit Methods for</u> <u>Qualitative Modeling of Gene Regulatory Networks</u>." In *Gene Regulatory Networks: Methods and Protocols*, edited by Bart Deplancke and Nele Gheldof, 397–443. Methods in Molecular Biology. Totowa, NJ: Humana Press.

Summary



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